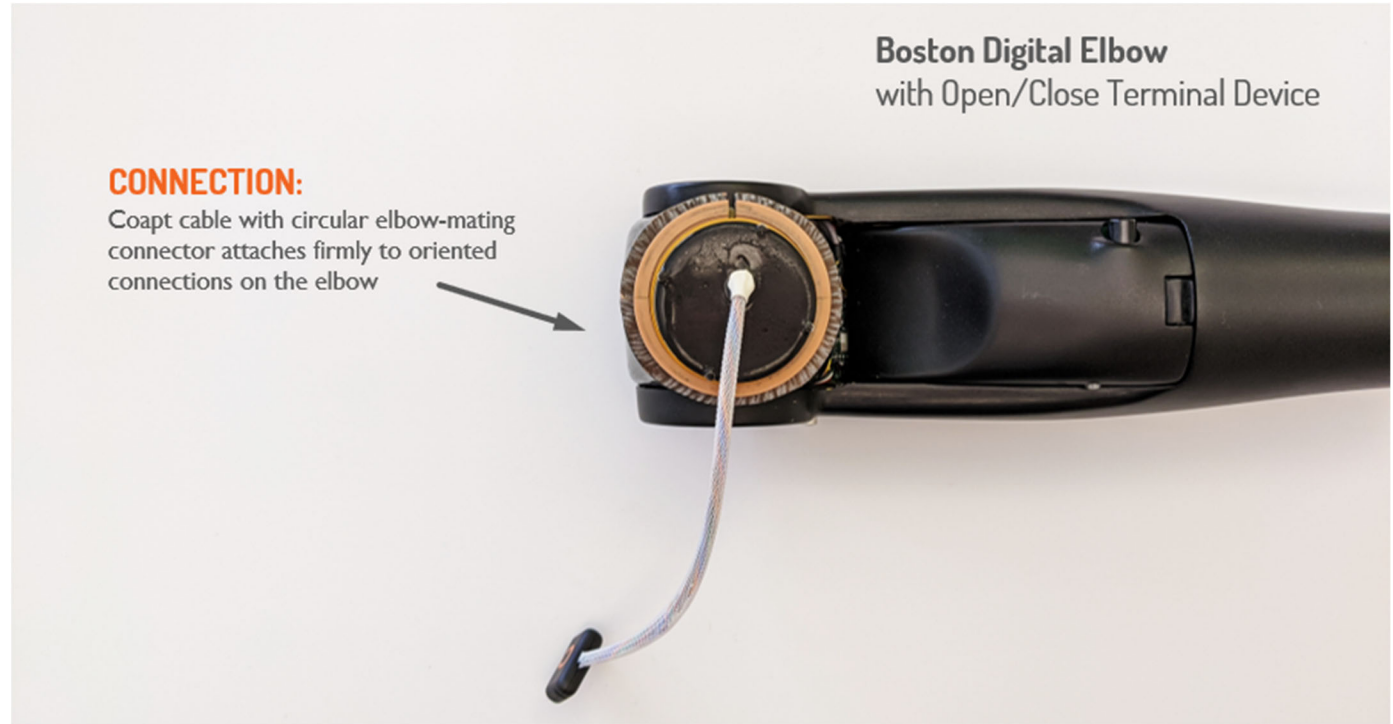


# DEVICE CONNECTION CABLE TYPE: K2

## PHYSICAL CONNECTIONS



## SOFTWARE SETTINGS

### **BOSTON DIGITAL ELBOW SETTINGS:**

The Boston Digital Elbow should be supplied directly from LTI and pre-setup with correct internal programming and cabling for Coapt use. Contact LTI support with any questions.

### **I-LIMB HAND SETTINGS:**

For open/close operation of i-Limb hand via Coapt , set device to its defaults.

### **OTTOBOCK HAND SETTINGS:**

For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its 'control mode'/'program' is to 1. (see further below for bebionic)

### **TASKA HAND SETTINGS:**

For open/close operation of TASKA hand via Coapt, set device to its defaults.

### **BEBIONIC HAND SETTINGS:**

For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at "Connection Guide" in the Coapt Complete ControlRoom Gen2 user interface application.