PHYSICAL CONNECTIONS

BOSTON DIGITAL ELBOW SETTINGS:
The Boston Digital Elbow should be supplied directly from LTI and pre-setup with correct internal programming and cabling for Coapt use. Contact LTI support with any questions.

I-LIMB HAND SETTINGS:
For open/close operation of i-Limb hand via Coapt, set device to its defaults.

OTTOBOCK HAND SETTINGS:
For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its 'control mode'/program' to 1. (see further below for bebionic)

TASKA HAND SETTINGS:
For open/close operation of TASKA hand via Coapt, set device to its defaults.

BEBIONIC HAND SETTINGS:
For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.