

DEVICE CONNECTION CABLE TYPE: J5

PHYSICAL CONNECTIONS

PRE-ASSEMBLED:

The Coapt controller (white PCB) will be pre-attached to the Espire unit. Do NOT attempt to remove it.

PRE-ASSEMBLED CONNECTION:

The Coapt COMPLETE CALIBRATE button is attached to the Coapt controller with its flex cable passing through the Espire Strain Relief Disc. Contact Coapt support for assistance detaching /attached this cable from the elbow.



EMG CONNECTION:

The Coapt EMG Interface Cable (not shown here) for Espire has a special 90° exit. Ensure it is connected and secured once the Espire Strain Relief Disc is in place.

SOFTWARE SETTINGS

ESPIRE HYBRID SETTINGS:

In the Espire iOS user application, most screens will indicate the direct Coapt connection and not require specific settings.

I-LIMB HAND SETTINGS:

For open/close operation of i-Limb hand via Coapt, set device to its defaults.

OTTOBOCK HAND SETTINGS:

For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its 'control mode'/'program' is to I. (see further below for bebionic)

TASKA HAND SETTINGS:

For open/close operation of TASKA hand via Coapt, set device to its defaults.

BEBIONIC HAND SETTINGS:

For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at "Connection Guide" in the Coapt Complete ControlRoom Gen2 user interface application.