DEVICE CONNECTION CABLE TYPE: J5

**PHYSICAL CONNECTIONS**

**PRE-ASSEMBLED:**
The Coapt controller (white PCB) will be pre-attached to the Espire unit. Do NOT attempt to remove it.

**PRE-ASSEMBLED CONNECTION:**
The Coapt COMPLETE CALIBRATE button is attached to the Coapt controller with its flex cable passing through the Espire Strain Relief Disc. Contact Coapt support for assistance detaching/attached this cable from the elbow.

**EMG CONNECTION:**
The Coapt EMG Interface Cable (not shown here) for Espire has a special 90° exit. Ensure it is connected and secured once the Espire Strain Relief Disc is in place.

**DISTAL CONNECTIONS**

**ESPIRE HYBRID SETTINGS:**
In the Espire iOS user application, most screens will indicate the direct Coapt connection and not require specific settings.

**I-LIMB HAND SETTINGS:**
For open/close operation of i-Limb hand via Coapt, set device to its defaults.

**OTTOBOCK HAND SETTINGS:**
For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its ‘control mode’/‘program’ is to 1. (see further below for bebionic)

**TASKA HAND SETTINGS:**
For open/close operation of TASKA hand via Coapt, set device to its defaults.

**BEBIONIC HAND SETTINGS:**
For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.