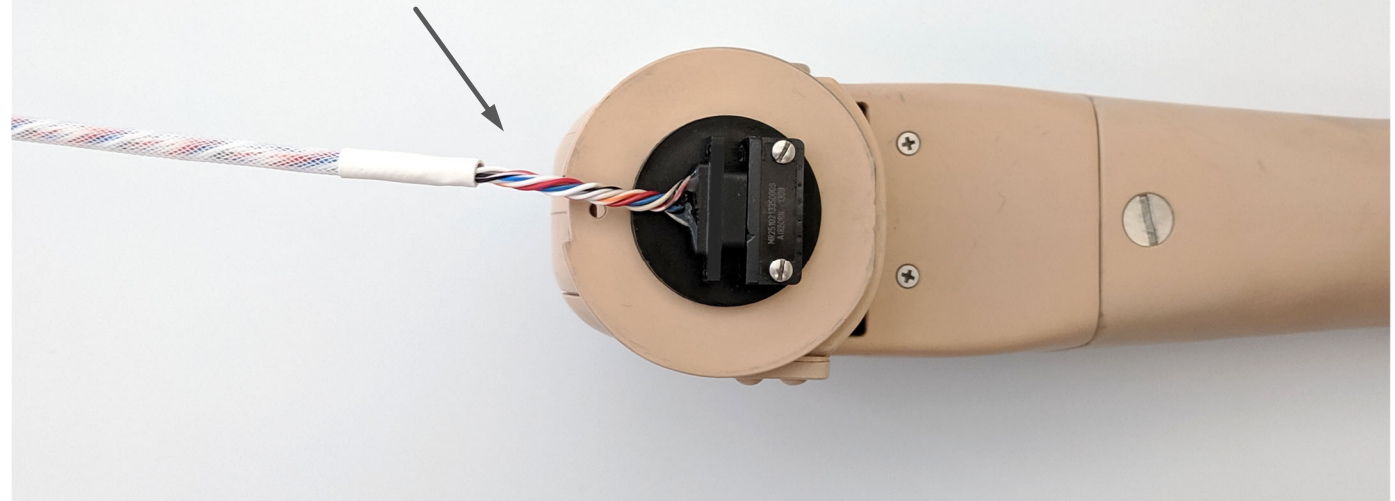


# DEVICE CONNECTION CABLE TYPE: J3

## PHYSICAL CONNECTIONS

### CONNECTION:

Coapt cable with 21-pin connector attaches firmly to mating connection on the elbow



Motion Control Utah Hybrid Arm

## SOFTWARE SETTINGS

### MOTION CONTROL SETTINGS:

For proper operation via Coapt refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.

### I-LIMB HAND SETTINGS:

For open/close operation of i-Limb hand via Coapt , set device to its defaults.

### OTTOBOCK HAND SETTINGS:

For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its ‘control mode’/‘program’ is to 1. (see further below for bebionic)

### TASKA HAND SETTINGS:

For open/close operation of TASKA hand via Coapt, set device to its defaults.

### BEBIONIC HAND SETTINGS:

For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.