Motion Control Utah Hybrid Arm

**DEVICE CONNECTION CABLE TYPE: J3**

**PHYSICAL CONNECTIONS**

**CONNECTION:**
Coapt cable with 21-pin connector attaches firmly to mating connection on the elbow

**SOFTWARE SETTINGS**

**MOTION CONTROL SETTINGS:**
For proper operation via Coapt refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.

**I-LIMB HAND SETTINGS:**
For open/close operation of i-Limb hand via Coapt, set device to its defaults.

**OTTOBOCK HAND SETTINGS:**
For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its ‘control mode’/‘program’ is to 1. (see further below for bebionic)

**TASKA HAND SETTINGS:**
For open/close operation of TASKA hand via Coapt, set device to its defaults.

**BEBIONIC HAND SETTINGS:**
For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.