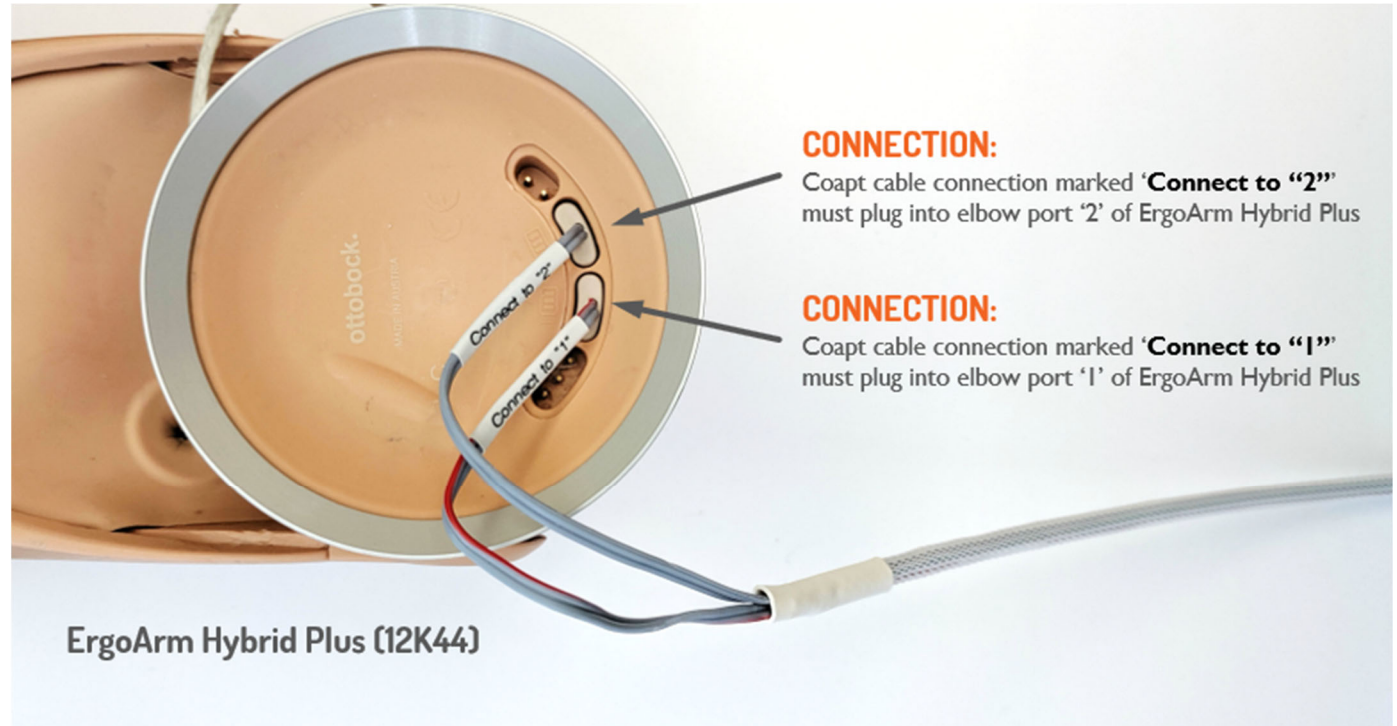


# DEVICE CONNECTION CABLE TYPE: J2

## PHYSICAL CONNECTIONS



### CONNECTION:

Coapt cable connection marked **'Connect to "2"'** must plug into elbow port '2' of ErgoArm Hybrid Plus

### CONNECTION:

Coapt cable connection marked **'Connect to "1"'** must plug into elbow port '1' of ErgoArm Hybrid Plus

ErgoArm Hybrid Plus (12K44)

## SOFTWARE SETTINGS

### MYOROTRONIC WRIST SETTINGS:

For proper rotation and hand operation via Coapt, the Ottobock MyoRotronic must be set to its 'program 1' default settings. Please refer to the MyoRotronic manual for more instructions

### MOTION CONTROL PROWRIST SETTINGS:

For proper rotation and hand operation via Coapt, refer to settings shown in the on-screen guide available at "Connection Guide" in the Coapt Complete ControlRoom Gen2 user interface application

### I-LIMB HAND SETTINGS:

For open/close operation of i-Limb hand via Coapt, set device to its defaults.

### OTTOBOCK HAND SETTINGS:

For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its 'control mode'/'program' is to 1. (see further below for bebionic)

### TASKA HAND SETTINGS:

For open/close operation of TASKA hand via Coapt, set device to its defaults.

### MOTION CONTROL PROHAND/PROETD SETTINGS:

For open/close operation of ProHand, ProETD, or ProETD2 via Coapt, refer to settings shown in the on-screen guide available at "Connection Guide" in the Coapt Complete ControlRoom Gen2 user interface application

### BEBIONIC HAND SETTINGS:

For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at "Connection Guide" in the Coapt Complete ControlRoom Gen2 user interface application