Device Connection - Cable Type: J1

Physical Connections

ErgoArm Electronic Plus (12K50)

Software Settings

**Myorotronic Wrist Settings:**
For proper rotation and hand operation via Coapt, the Ottobock MyoRotronic must be set to its 'program 1' default settings. Please refer to the MyoRotronic manual for more instructions.

**Motion Control Prowrist Settings:**
For proper rotation and hand operation via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.

**I-limb Hand Settings:**
For open/close operation of i-Limb hand via Coapt, set device to its defaults.

**Ottobock Hand Settings:**
For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its 'control mode'/’program’ is to 1. (see further below for bebionic)

**Taska Hand Settings:**
For open/close operation of Taska hand via Coapt, set device to its defaults.

**Motion Control Prohand/Proetd Settings:**
For open/close operation of ProHand, ProETD, or ProETD2 via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.

**Bebionic Hand Settings:**
For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.