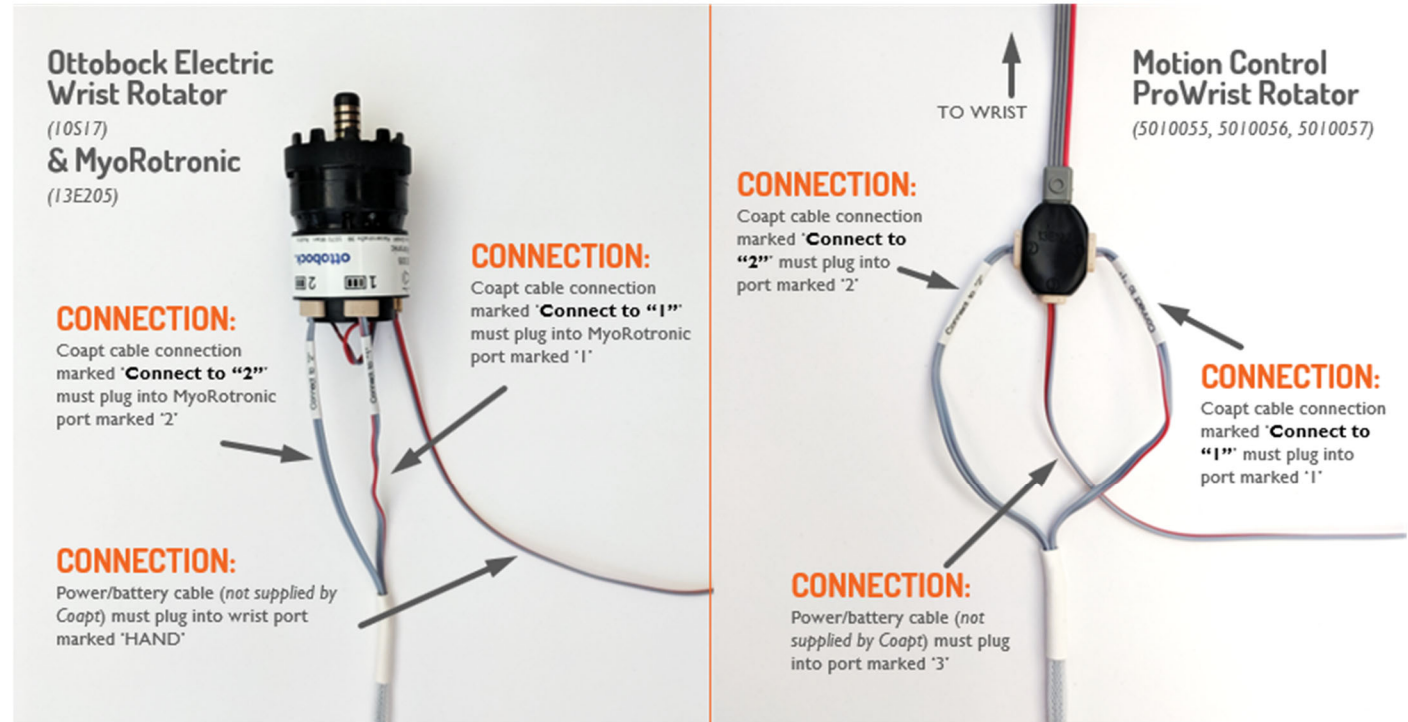


DEVICE CONNECTION CABLE TYPE: 11

PHYSICAL CONNECTIONS



SOFTWARE SETTINGS

MYOROTRONIC WRIST SETTINGS:

For proper rotation and hand operation via Coapt, the Ottobock MyoRotronic must be set to its 'program 1' default settings. Please refer to the MyoRotronic manual for more instructions

MOTION CONTROL PROWRIST SETTINGS:

For proper rotation and hand operation via Coapt, refer to settings shown in the on-screen guide available at "Connection Guide" in the Coapt Complete ControlRoom Gen2 user interface application

I-LIMB HAND SETTINGS:

For open/close operation of i-Limb hand via Coapt, set device to its defaults.

OTTOBOCK HAND SETTINGS:

For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its 'control mode'/'program' is to 1. (see further below for bebionic)

TASKA HAND SETTINGS:

For open/close operation of TASKA hand via Coapt, set device to its defaults.

MOTION CONTROL PROHAND/PROETD SETTINGS:

For open/close operation of ProHand, ProETD, or ProETD2 via Coapt, refer to settings shown in the on-screen guide available at "Connection Guide" in the Coapt Complete ControlRoom Gen2 user interface application

BEBIONIC HAND SETTINGS:

For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at "Connection Guide" in the Coapt Complete ControlRoom Gen2 user interface application