**DEVICE CONNECTION CABLE TYPE: I1**

**PHYSICAL CONNECTIONS**

**Ottobock Electric Wrist Rotator**
(10517) & MyoRotronic  
(13E205)

**Connection:**
Coapt cable connection marked **Connect to “1”** must plug into MyoRotronic port marked ‘1’

**Connection:**
Power/battery cable (not supplied by Coapt) must plug into wrist port marked ‘HAND’

**Motion Control ProWrist Rotator**
(5010055, 5010056, 5010057)

**Connection:**
Coapt cable connection marked **Connect to “2”** must plug into port marked ‘2’

**Connection:**
Coapt cable connection marked **Connect to “1”** must plug into port marked ‘1’

**SOFTWARE SETTINGS**

**MYOROTRONIC WRIST SETTINGS:**
For proper rotation and hand operation via Coapt, the Ottobock MyoRotronic must be set to its ‘program 1’ default settings. Please refer to the MyoRotronic manual for more instructions.

**MOTION CONTROL PROWRIST SETTINGS:**
For proper rotation and hand operation via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.

**I-LIMB HAND SETTINGS:**
For open/close operation of i-Limb hand via Coapt, set device to its defaults.

**OTTOBOCK HAND SETTINGS:**
For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its ‘control mode’/‘program’ is to 1. (see further below for bebionic)

**TASKA HAND SETTINGS:**
For open/close operation of TASKA hand via Coapt, set device to its defaults.

**MOTION CONTROL PROHAND/PROETD SETTINGS:**
For open/close operation of ProHand, ProETD, or ProETD2 via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.

**BEBIONIC HAND SETTINGS:**
For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.