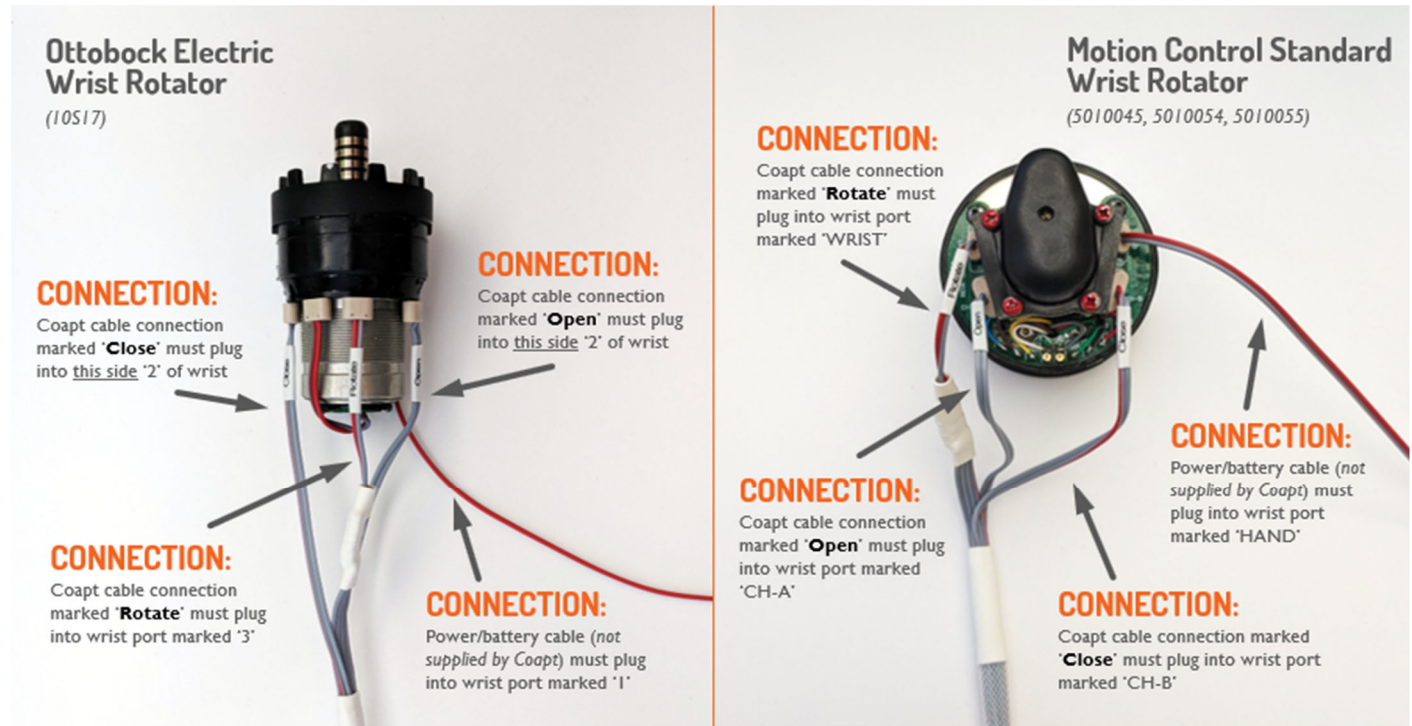


# DEVICE CONNECTION CABLE TYPE: IO

## PHYSICAL CONNECTIONS



## SOFTWARE SETTINGS

### WRIST SETTINGS:

No manual settings necessary for the Ottobock Standard Wrist Rotator or the Motion Control Standard Wrist Rotator

### I-LIMB HAND SETTINGS:

For open/close operation of i-Limb hand via Coapt, set device to its defaults.

### OTTOBOCK HAND SETTINGS:

For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its 'control mode'/'program' is to 1. (see further below for bebionic)

### TASKA HAND SETTINGS:

For open/close operation of TASKA hand via Coapt, set device to its defaults.

### MOTION CONTROL PROHAND/PROETD SETTINGS:

For open/close operation of ProHand, ProETD, or ProETD2 via Coapt, refer to settings shown in the on-screen guide available at "Connection Guide" in the Coapt Complete ControlRoom Gen2 user interface application

### BEBIONIC HAND SETTINGS:

For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at "Connection Guide" in the Coapt Complete ControlRoom Gen2 user interface application