**DEVICE CONNECTION CABLE TYPE: IO**

**PHYSICAL CONNECTIONS**

**Ottobock Electric Wrist Rotator**

**Connection:**
- Coapt cable connection marked ‘Close’ must plug into this side ‘2’ of wrist.
- Coapt cable connection marked ‘Rotate’ must plug into this side ‘3’ of wrist.
- Coapt cable connection marked ‘Open’ must plug into wrist port marked ‘1’.

**Motion Control Standard Wrist Rotator**

**Connection:**
- Coapt cable connection marked ‘Rotate’ must plug into wrist port marked ‘WRIST’.
- Power/battery cable (not supplied by Coapt) must plug into wrist port marked ‘CH-A’.
- Coapt cable connection marked ‘Open’ must plug into wrist port marked ‘CH-B’.

**SOFTWARE SETTINGS**

**WRIST SETTINGS:**
No manual settings necessary for the Ottobock Standard Wrist Rotator or the Motion Control Standard Wrist Rotator.

**I-LIMB HAND SETTINGS:**
For open/close operation of i-Limb hand via Coapt, set device to its defaults.

**OTTOBOCK HAND SETTINGS:**
For open/close operation of SensorHand, MyoHand VariPlus, System Electric Greifer, or System Electric Hand devices via Coapt, set its ‘control mode’/’program’ is to 1. (see further below for bebionic).

**TASKA HAND SETTINGS:**
For open/close operation of TASKA hand via Coapt, set device to its defaults.

**MOTION CONTROL PROHAND/PROETD SETTINGS:**
For open/close operation of ProHand, ProETD, or ProETD2 via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.

**BEBIONIC HAND SETTINGS:**
For open/close operation of bebionic via Coapt, refer to settings shown in the on-screen guide available at “Connection Guide” in the Coapt Complete ControlRoom Gen2 user interface application.