

transhumeral and proximal

**Elbow
Flexion/
Extension**








**Elbow
Locking/
Unlocking**

transradial and distal

**Wrist
Actuation**

**Terminal Device
Open/Close**

**Terminal Device
Multiple Grasps**

	Elbow Flexion/Extension	Elbow Locking/Unlocking	Wrist Actuation	Terminal Device Open/Close	Terminal Device Multiple Grasps
	LUKE arm		LUKE arm ²	LUKE arm	
		AxonArm Hybrid (12K500) AxonArm Ergo ¹ (12K501)	AxonRotation	Michelangelo Hand AxonHook	Michelangelo Hand
		ErgoArm Hybrid plus (12K44) ErgoArm Electronic plus ¹ (12K50)	Electric Wrist Rotator with MyoRotronic	bebionic SensorHand Speed MyoHand VariPlus Speed System Electric Greifer System Electric Hand	bebionic
	DynamicArm (12K100) DynamicArm Plus (12K110)	Electric Wrist Rotator ³			
				i-limb hands (access, pulse, ultra, revolution, quantum ⁵)	
		Boston Digital Arm			
		Utah Arm 3+ Motion E2 Elbow	MC Standard Wrist Rotator ³	ProPlus Hand ProPlus ETD/ETD2	
		Utah Hybrid Arm ¹	MC Standard Wrist Rotator with 6-Band Coaxial Plug option ⁴		
				TASKA	TASKA
				VINCENTevolution 2	VINCENTevolution 2

1. Pattern recognition command of elbow lock/unlock is possible.
2. Pattern recognition command of 2 degree-of-freedom wrist.
3. May require Coapt motor controller (Coapt part number CC125) when used without powered elbow.
4. Required for pattern recognition grasp selection command of bebionic, TASKA, and VINCENT multifunction hands.
5. Pattern recognition command for fast-entry into i-mo is possible.